

VECTORS

I. Position Vector Of A Point:

let O be a fixed origin, then the position vector of a point P is the vector

\vec{OP} . If \vec{a} and \vec{b} are position vectors of two points A and B, then,

$$\vec{AB} = \vec{b} - \vec{a} = \text{pv of B} - \text{pv of A.}$$

DISTANCE FORMULA : Distance between the two points A (\vec{a}) and B (\vec{b})

$$\text{is } AB = \left| \vec{a} - \vec{b} \right|$$

SECTION FORMULA : $\vec{r} = \frac{n\vec{a} + m\vec{b}}{m+n}$. Mid point of AB = $\frac{\vec{a} + \vec{b}}{2}$.

II. **Scalar Product Of Two Vectors:** $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$, where $|\vec{a}|, |\vec{b}|$ are magnitude of \vec{a} and \vec{b} respectively and θ is angle between \vec{a} and \vec{b} .

1. $i \cdot i = j \cdot j = k \cdot k = 1$; $i \cdot j = j \cdot k = k \cdot i = 0$ projection of \vec{a} on $\vec{b} = \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|}$

2. If $\vec{a} = a_1i + a_2j + a_3k$ & $\vec{b} = b_1i + b_2j + b_3k$ then $\vec{a} \cdot \vec{b} = a_1b_1 + a_2b_2 + a_3b_3$

3. The angle ϕ between \vec{a} & \vec{b} is given by $\cos \phi = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|}$, $0 \leq \phi \leq \pi$

4. $\vec{a} \cdot \vec{b} = 0 \Leftrightarrow \vec{a} \perp \vec{b}$ ($\vec{a} \neq 0, \vec{b} \neq 0$)

III. **Vector Product Of Two Vectors:**

1. If \vec{a} & \vec{b} are two vectors & θ is the angle between them then $\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta \vec{n}$, where \vec{n} is the unit vector perpendicular to both \vec{a} & \vec{b} such that \vec{a}, \vec{b} & \vec{n} forms a right handed screw system.

2. Geometrically $|\vec{a} \times \vec{b}|$ = area of the parallelogram whose two adjacent sides are represented by \vec{a} & \vec{b} .

3. $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = \vec{0}$; $\hat{i} \times \hat{j} = \hat{k}, \hat{j} \times \hat{k} = \hat{i}, \hat{k} \times \hat{i} = \hat{j}$

4. If $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ & $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ then

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

5. $\vec{a} \times \vec{b} = \vec{0} \Leftrightarrow \vec{a}$ and \vec{b} are parallel (collinear)

($\vec{a} \neq 0, \vec{b} \neq 0$) i.e. $\vec{a} = K\vec{b}$, where K is a scalar.

6. Unit vector perpendicular to the plane of \vec{a} & \vec{b} is $\hat{n} = \pm \frac{\vec{a} \times \vec{b}}{|\vec{a} \times \vec{b}|}$

☞ If $\vec{a}, \vec{b}, \vec{c}$ are the pv's of 3 points A, B & C then the vector area of triangle

$$ABC = \frac{1}{2} [\vec{a} \times \vec{b} + \vec{b} \times \vec{c} + \vec{c} \times \vec{a}]$$

The points A, B & C are collinear if $\vec{a} \times \vec{b} + \vec{b} \times \vec{c} + \vec{c} \times \vec{a} = \vec{0}$

☞ Area of any quadrilateral whose diagonal vectors are \vec{d}_1 & \vec{d}_2 is given by

$$\frac{1}{2} |\vec{d}_1 \times \vec{d}_2|$$

☞ Lagrange's Identity : $(\vec{a} \times \vec{b})^2 = |\vec{a}|^2 |\vec{b}|^2 - (\vec{a} \cdot \vec{b})^2 = \begin{vmatrix} \vec{a} \cdot \vec{a} & \vec{a} \cdot \vec{b} \\ \vec{a} \cdot \vec{b} & \vec{b} \cdot \vec{b} \end{vmatrix}$

IV. Scalar Triple Product:

☞ The scalar triple product of three vectors \vec{a} , \vec{b} & \vec{c} is defined as:

$$\vec{a} \times \vec{b} \cdot \vec{c} = |\vec{a}| |\vec{b}| |\vec{c}| \sin \theta \cos \phi$$

☞ Volume of tetrahedron $V = \frac{1}{6} |\vec{a} \cdot \vec{b} \times \vec{c}|$

☞ In a scalar triple product the position of dot & cross can be interchanged i.e.

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = (\vec{a} \times \vec{b}) \cdot \vec{c} \quad \text{OR} \quad [\vec{a} \ \vec{b} \ \vec{c}] = [\vec{b} \ \vec{c} \ \vec{a}] = [\vec{c} \ \vec{a} \ \vec{b}]$$

☞ $\vec{a} \cdot (\vec{b} \times \vec{c}) = -\vec{a} \cdot (\vec{c} \times \vec{b})$ i.e. $[\vec{a} \ \vec{b} \ \vec{c}] = -[\vec{a} \ \vec{c} \ \vec{b}]$

☞ If $\vec{a} = a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$; $\vec{b} = b_1 \hat{i} + b_2 \hat{j} + b_3 \hat{k}$ & $\vec{c} = c_1 \hat{i} + c_2 \hat{j} + c_3 \hat{k}$ then $[\vec{a} \ \vec{b} \ \vec{c}] = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$

☞ If \vec{a} , \vec{b} , \vec{c} are coplanar $\Leftrightarrow [\vec{a} \ \vec{b} \ \vec{c}] = 0$.

☞ Volume of tetrahedron OABC with O as origin & A(\vec{a}), B(\vec{b}) and C(\vec{c})

be the vertices = $\left| \frac{1}{6} [\vec{a} \ \vec{b} \ \vec{c}] \right|$

☞ The position vector of the centroid of a tetrahedron if the pv's of its vertices are \vec{a} , \vec{b} , \vec{c} & \vec{d} are given by $\frac{1}{4} [\vec{a} + \vec{b} + \vec{c} + \vec{d}]$.

V. Vector Triple Product:

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}, (\vec{a} \times \vec{b}) \times \vec{c} = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{b} \cdot \vec{c})\vec{a}$$

☞ $(\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c})$, in general

3-DIMENSION

1. Vector representation of a point :

Position vector of point P (x, y, z) is $x\hat{i} + y\hat{j} + z\hat{k}$.

2. Distance formula :

$$\sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}, \quad AB = |\vec{OB} - \vec{OA}|$$

3. Distance of P from coordinate axes :

$$PA = \sqrt{y^2 + z^2}, PB = \sqrt{z^2 + x^2}, PC = \sqrt{x^2 + y^2}$$

4. Section Formula : $x = \frac{mx_2 + nx_1}{m+n}, y = \frac{my_2 + ny_1}{m+n}, z = \frac{mz_2 + nz_1}{m+n}$

$$\text{Mid point: } x = \frac{x_1 + x_2}{2}, y = \frac{y_1 + y_2}{2}, z = \frac{z_1 + z_2}{2}$$

5. Direction Cosines And Direction Ratios

(i) Direction cosines: Let α, β, γ be the angles which a directed line makes with the positive directions of the axes of x, y and z respectively, then $\cos \alpha, \cos \beta, \cos \gamma$ are called the direction cosines of the line. The direction cosines are usually denoted by (l, m, n) . Thus $l = \cos \alpha, m = \cos \beta, n = \cos \gamma$.

(ii) If l, m, n be the direction cosines of a line, then $l^2 + m^2 + n^2 = 1$

(iii) Direction ratios: Let a, b, c be proportional to the direction cosines l, m, n then a, b, c are called the direction ratios.

(iv) If l, m, n be the direction cosines and a, b, c be the direction ratios of a vector, then

$$l = \pm \frac{a}{\sqrt{a^2 + b^2 + c^2}}, m = \pm \frac{b}{\sqrt{a^2 + b^2 + c^2}}, n = \pm \frac{c}{\sqrt{a^2 + b^2 + c^2}}$$

- (vi) If the coordinates P and Q are (x_1, y_1, z_1) and (x_2, y_2, z_2) then the direction ratios of line PQ are, $a = x_2 - x_1$, $b = y_2 - y_1$ & $c = z_2 - z_1$ and

$$\text{the direction cosines of line PQ are } \ell = \frac{x_2 - x_1}{|PQ|},$$

$$m = \frac{y_2 - y_1}{|PQ|} \text{ and } n = \frac{z_2 - z_1}{|PQ|}$$

6. Angle Between Two Line Segments:

$$\cos \theta = \left| \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}} \right|.$$

The line will be perpendicular if $a_1 a_2 + b_1 b_2 + c_1 c_2 = 0$,

$$\text{parallel if } \frac{a_1}{a_2} = \frac{b_1}{b_2} = \frac{c_1}{c_2}$$

7. Projection of a line segment on a line

If $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$ then the projection of PQ on a line having direction cosines ℓ, m, n is

$$\left| \ell(x_2 - x_1) + m(y_2 - y_1) + n(z_2 - z_1) \right|$$

8. Equation Of A Plane : General form: $ax + by + cz + d = 0$, where a, b, c are not all zero, $a, b, c, d \in R$.

(i) Normal form : $\ell x + my + nz = p$

(ii) Plane through the point (x_1, y_1, z_1) :

$$a(x - x_1) + b(y - y_1) + c(z - z_1) = 0$$

(iii) Intercept Form: $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$

(iv) Vector form: $(\vec{r} - \vec{a}) \cdot \vec{n} = 0$ or $\vec{r} \cdot \vec{n} = \vec{a} \cdot \vec{n}$

(v) Any plane parallel to the given plane $ax + by + cz + d = 0$ is $ax + by + cz + \lambda = 0$. Distance between $ax + by + cz + d_1 = 0$ and

$$ax + by + cz + d_2 = 0 \text{ is } = \frac{|d_1 - d_2|}{\sqrt{a^2 + b^2 + c^2}}$$

- (vi) **Equation of a plane passing through a given point & parallel to the given vectors:**

$$\vec{r} = \vec{a} + \lambda \vec{b} + \mu \vec{c} \quad (\text{parametric form}) \quad \text{where } \lambda \text{ \& } \mu \text{ are scalars.}$$

$$\text{or} \quad \vec{r} \cdot (\vec{b} \times \vec{c}) = \vec{a} \cdot (\vec{b} \times \vec{c}) \quad (\text{non parametric form})$$

9. A Plane & A Point

- (i) Distance of the point (x', y', z') from the plane $ax + by + cz + d = 0$ is

$$\text{given by } \frac{ax' + by' + cz' + d}{\sqrt{a^2 + b^2 + c^2}}.$$

- (ii) Length of the perpendicular from a point (\vec{a}) to plane $\vec{r} \cdot \vec{n} = d$

$$\text{is given by } p = \frac{|\vec{a} \cdot \vec{n} - d|}{|\vec{n}|}.$$

- (iii) Foot (x', y', z') of perpendicular drawn from the point (x_1, y_1, z_1) to

$$\text{the plane } ax + by + cz + d = 0 \text{ is given by } \frac{x' - x_1}{a} = \frac{y' - y_1}{b} = \frac{z' - z_1}{c}$$

$$= - \frac{(ax_1 + by_1 + cz_1 + d)}{a^2 + b^2 + c^2}$$

- (iv) **To find image of a point w.r.t. a plane:**

Let P (x_1, y_1, z_1) is a given point and $ax + by + cz + d = 0$ is given plane Let (x', y', z') is the image point. then

$$\frac{x' - x_1}{a} = \frac{y' - y_1}{b} = \frac{z' - z_1}{c} = -2 \frac{(ax_1 + by_1 + cz_1 + d)}{a^2 + b^2 + c^2}$$

10. Angle Between Two Planes:

$$\cos \theta = \left| \frac{aa' + bb' + cc'}{\sqrt{a^2 + b^2 + c^2} \sqrt{a'^2 + b'^2 + c'^2}} \right|$$

Planes are perpendicular if $aa' + bb' + cc' = 0$ and planes are parallel if

$$\frac{a}{a'} = \frac{b}{b'} = \frac{c}{c'}$$

The angle θ between the planes $\vec{r} \cdot \vec{n}_1 = d_1$ and $\vec{r} \cdot \vec{n}_2 = d_2$ is given by, \cos

$$\theta = \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1| \cdot |\vec{n}_2|}$$

Planes are perpendicular if $\vec{n}_1 \cdot \vec{n}_2 = 0$ & planes are parallel if

$$\vec{n}_1 = \lambda \vec{n}_2, \lambda \text{ is a scalar}$$

11. Angle Bisectors

(i) The equations of the planes bisecting the angle between two given planes

$$a_1x + b_1y + c_1z + d_1 = 0 \text{ and } a_2x + b_2y + c_2z + d_2 = 0 \text{ are}$$

$$\frac{a_1x + b_1y + c_1z + d_1}{\sqrt{a_1^2 + b_1^2 + c_1^2}} = \pm \frac{a_2x + b_2y + c_2z + d_2}{\sqrt{a_2^2 + b_2^2 + c_2^2}}$$

(ii) Bisector of acute/obtuse angle: First make both the constant terms positive. Then

$$a_1a_2 + b_1b_2 + c_1c_2 > 0 \quad \Rightarrow \quad \text{origin lies on obtuse angle}$$

$$a_1a_2 + b_1b_2 + c_1c_2 < 0 \quad \Rightarrow \quad \text{origin lies in acute angle}$$

12. Family of Planes

(i) Any plane through the intersection of $a_1x + b_1y + c_1z + d_1 = 0$ & $a_2x + b_2y + c_2z + d_2 = 0$ is

$$a_1x + b_1y + c_1z + d_1 + \lambda (a_2x + b_2y + c_2z + d_2) = 0$$

(ii) The equation of plane passing through the intersection of the planes $\vec{r} \cdot \vec{n}_1 = d_1$ & $\vec{r} \cdot \vec{n}_2 = d_2$ is $\vec{r} \cdot (n_1 + \lambda \vec{n}_2) = d_1 + \lambda d_2$ where λ is arbitrary scalar

13. **Volume Of A Tetrahedron:** Volume of a tetrahedron with vertices $A(x_1, y_1, z_1)$, $B(x_2, y_2, z_2)$, $C(x_3, y_3, z_3)$ and

$$D(x_4, y_4, z_4) \text{ is given by } V = \frac{1}{6} \begin{vmatrix} x_1 & y_1 & z_1 & 1 \\ x_2 & y_2 & z_2 & 1 \\ x_3 & y_3 & z_3 & 1 \\ x_4 & y_4 & z_4 & 1 \end{vmatrix}$$

A LINE

1. Equation Of A Line

(i) A straight line is intersection of two planes.
it is represented by two planes $a_1x + b_1y + c_1z + d_1 = 0$ and $a_2x + b_2y + c_2z + d_2 = 0$.

(ii) Symmetric form : $\frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c} = r$.

(iii) Vector equation: $\vec{r} = \vec{a} + \lambda \vec{b}$

(iv) Reduction of cartesian form of equation of a line to vector form & vice versa

$$\frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c} \Leftrightarrow \vec{r} = (x_1\hat{i} + y_1\hat{j} + z_1\hat{k}) + \lambda(a\hat{i} + b\hat{j} + c\hat{k}).$$

2. Angle Between A Plane And A Line:

(i) If θ is the angle between line $\frac{x-x_1}{\ell} = \frac{y-y_1}{m} = \frac{z-z_1}{n}$ and the plane $ax + by + cz + d = 0$, then

$$\sin \theta = \left| \frac{a\ell + bm + cn}{\sqrt{(a^2 + b^2 + c^2)} \sqrt{\ell^2 + m^2 + n^2}} \right|.$$

(ii) Vector form: If θ is the angle between a line $\vec{r} = (\vec{a} + \lambda \vec{b})$ and

$$\vec{r} \cdot \vec{n} = d \text{ then } \sin \theta = \left[\frac{\vec{b} \cdot \vec{n}}{|\vec{b}| |\vec{n}|} \right].$$

(iii) Condition for perpendicularity $\frac{\ell}{a} = \frac{m}{b} = \frac{n}{c}$, $\vec{b} \times \vec{n} = 0$

(iv) Condition for parallel $a\ell + bm + cn = 0$ $\vec{b} \cdot \vec{n} = 0$

3. Condition For A Line To Lie In A Plane

(i) Cartesian form: Line $\frac{x-x_1}{\ell} = \frac{y-y_1}{m} = \frac{z-z_1}{n}$ would lie in a plane $ax + by + cz + d = 0$, if $ax_1 + by_1 + cz_1 + d = 0$ & $a\ell + bm + cn = 0$.

(ii) Vector form: Line $\vec{r} = \vec{a} + \lambda \vec{b}$ would lie in the plane $\vec{r} \cdot \vec{n} = d$ if $\vec{b} \cdot \vec{n} = 0$ & $\vec{a} \cdot \vec{n} = d$

4. Skew Lines:

- (i) The straight lines which are not parallel and non-coplanar i.e. non-intersecting are called skew lines.

$$\text{lines } \frac{x-\alpha}{\ell} = \frac{y-\beta}{m} = \frac{z-\gamma}{n} \quad \& \quad \frac{x-\alpha'}{\ell'} = \frac{y-\beta'}{m'} = \frac{z-\gamma'}{n'}$$

$$\text{If } \Delta = \begin{vmatrix} \alpha'-\alpha & \beta'-\beta & \gamma'-\gamma \\ \ell & m & n \\ \ell' & m' & n' \end{vmatrix} \neq 0, \text{ then lines are skew.}$$

- (ii) Shortest distance formula for lines

$$\vec{r} = \vec{a}_1 + \lambda \vec{b}_1 \text{ and } \vec{r} = \vec{a}_2 + \lambda \vec{b}_2 \text{ is } d = \frac{|(\vec{a}_2 - \vec{a}_1) \cdot (\vec{b}_1 \times \vec{b}_2)|}{|\vec{b}_1 \times \vec{b}_2|}$$

- (iii) Vector Form: For lines $\vec{r} = \vec{a}_1 + \lambda \vec{b}_1$ and $\vec{r} = \vec{a}_2 + \lambda \vec{b}_2$ to be skew

$$(\vec{b}_1 \times \vec{b}_2) \cdot (\vec{a}_2 - \vec{a}_1) \neq 0$$

- (iv) Shortest distance between parallel lines

$$\vec{r} = \vec{a}_1 + \lambda \vec{b} \text{ \& } \vec{r} = \vec{a}_2 + \mu \vec{b} \text{ is } d = \frac{|(\vec{a}_2 - \vec{a}_1) \times \vec{b}|}{|\vec{b}|}$$

- (v) Condition of coplanarity of two lines $\vec{r} = \vec{a} + \lambda \vec{b}$ & $\vec{r} = \vec{c} + \mu \vec{d}$ is

$$[\vec{a} - \vec{c} \quad \vec{b} \quad \vec{d}] = 0$$

5. Sphere

General equation of a sphere is $x^2 + y^2 + z^2 + 2ux + 2vy + 2wz + d = 0$.

$(-u, -v, -w)$ is the centre and $\sqrt{u^2 + v^2 + w^2 - d}$ is the radius of the sphere.